

Automatic Grass Cutter

Beg Alina¹, Choudhari Vinay², Akolkar Prajwal³, Nannaware Harshal⁴, Pachbail Sanket⁵, Pagire Sumit⁶

^{1,2}Assistant Professor, Mechanical Engineering, VACOE, Ahilyanagar, Maharashtra, India.

^{3,4,5,6}Diploma - Mechanical Engineering, VACOE, Ahilyanagar, Maharashtra, India.

Emails: afbeg124@gmail.com¹, vsc.vacoe@gmail.com², akolkarprajwal744@gmail.com³, nannawareharshal1551@gmail.com⁴, sanketpa68@gmail.com⁵, pagiresumit2005@gmail.com⁶

Abstract

In today's fast-paced world, the demand for user-friendly and efficient tools to streamline routine tasks is ever-growing. This paper introduces the development of an innovative automatic grass-cutting device designed for single-hand operation. Engineered for ease of handling and precise control, this device combines compactness, lightweight construction, and advanced automation technology to enhance usability. The design focuses on minimizing physical effort while ensuring optimal performance, making it an ideal solution for household lawns, small gardens, and urban green spaces. The proposed system incorporates intelligent mechanisms for cutting height adjustment and energy efficiency, setting it apart as an eco-friendly and ergonomically superior alternative to traditional grass cutters. This research details the design, functionality, and real-world applications of the device, showcasing its potential impact on personal landscaping tools. The device's intuitive interface simplifies operations for users of all skill levels, making it accessible to a wider demographic.

Keywords: Compact, Efficient, Sustainable, User friendly.

1. Introduction

Grass cutting is a fundamental aspect of landscape maintenance, essential for ensuring aesthetic appeal and proper upkeep of outdoor spaces. Traditionally, this task has relied heavily on manual labor and conventional tools, which can be time-consuming, labor-intensive, and prone to inefficiencies. With the growing demand for modern solutions that enhance productivity and reduce physical effort, the concept of an Automatic Grass Cutter has emerged as an innovative answer to these challenges [1][3]. This project focuses on the energy-efficient cutting mechanisms, and renewable power sources, the automatic grass cutter serves as a sustainable, user-friendly, and efficient alternative to traditional methods. The development of this system highlights critical engineering skills such as design optimization, material selection, system integration, and performance testing, offering a practical application of theoretical knowledge gained throughout the academic journey. The project not only provides a solution for effective grass cutting but

also contributes to the broader pursuit of automation and innovation in mechanical engineering [2].

1.1 Aim

To design and develop an efficient automatic grass-cutting system capable of autonomous operation to reduce manual effort and enhance productivity.

1.2 Objectives

To integrate a durable and energy-efficient cutting mechanism optimized for various grass densities and lengths. To develop a mobility system that ensures smooth navigation across uneven terrains. To utilize sustainable energy sources, such as solar power, for environmentally friendly operation. To create a user-friendly interface allowing customization of cutting patterns and grass height. To apply mechanical engineering principles in design, fabrication, and performance testing.

2. Method

Electrical energy of the battery is converted to mechanical energy through a set of blades designed to achieve cutting operation. The electric circuit

ensures power transfer from the battery to run the D.C. motor, whilst the alternator utilizes the mechanical power to continuously recharge the battery while in operation. The cutting blades tap power from the D.C. motor. When the power switch is on, the electrical energy from the battery powers the motor which in turn actuates both the blades and the alternator shafts [4]. The rotating motion of the alternator shaft generates current to recharge the battery, thereby compensating for the battery discharge. The rotating blades continuously cut the grass as the mower is propelled forward and the cut grass is channeled to the collection box/bag attached at the rear of the machine. Height of cut is adjusted by means of the link mechanism via the lift rod. Figure 1 shows Block Diagram.

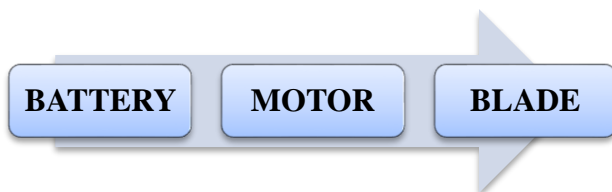


Figure 1 Block Diagram

The operating principle of an Automatic Grass Cutter lies in its efficient, lightweight, and user-centric design, developed to simplify the task of grass cutting while maximizing convenience and ease of operation. This device is powered by an energy-efficient motor that drives a robust cutting blade assembly, which ensures uniform and precise grass trimming. One of the standout features of this machine is its lightweight construction, which not only makes it highly portable but also allows for single-hand operation, eliminating the fatigue and inconvenience associated with heavier, more complex lawn maintenance equipment. The simplicity of its construction is another key advantage, as it consists of minimal mechanical components, ensuring hassle-free assembly, straightforward usage, and reduced maintenance requirements. The device is particularly suitable for residential and small-scale lawn care, where users prioritize reliability, ease of use, and practical functionality over intricate, high-tech systems. Its intuitive design allows users to operate it effectively without requiring technical expertise, making it

accessible to a wide range of individuals. The adjustable cutting height further enhances its versatility, enabling users to achieve their desired lawn appearance effortlessly. Additionally, its compact and durable frame allows the grass cutter to be stored easily and withstand regular usage. This design philosophy combines efficiency, functionality, and convenience, making the Automatic Grass Cutter a reliable and cost-effective solution for modern lawn maintenance needs. Figure 2 shows 2D Design.

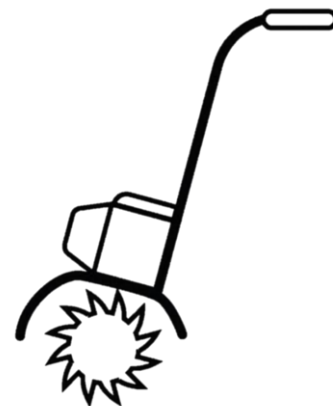


Figure 2 2D Design

2.1 Modification In Design After Trial

The original grass cutter design featured an exposed cutting mechanism without any protective cover in front of the blade. This lack of shielding presented significant safety risks, including increased chances of injury from accidental direct contact with the rotating blade or from debris expelled during operation. To mitigate these hazards, the design was revised to incorporate a protective hub placed at the front of the cutter assembly [5].

- **Design Modification Overview:** Objective: To enhance user safety by preventing direct contact with the moving blade and reducing the impact of flying debris, a hub was added to the front of the grass cutter.
- **Implementation:** The protective hub is integrated directly into the cutter's frontal assembly. It acts as a physical barrier, intercepting any accidental contact and deflecting debris away from the operator and critical machine components.

- **Technical Details:** Hub Structure and Material Selection: Construction: The hub is fabricated from high-strength, impact-resistant materials such as engineered plastics or light alloys to ensure durability without excessively increasing the overall weight of the device. **Weight Consideration:** Material selection for the hub is optimized to maintain a low additional weight, helping to preserve the cutter's overall balance and operational efficiency.
- **Integration with the Cutter Assembly:** **Alignment:** The hub is designed to align seamlessly with the rotating blade assembly. This careful alignment ensures that the protective barrier does not interfere with the cutting performance or induce imbalance during operation.
- **Aerodynamics:** The shape and placement of the hub are engineered to maintain aerodynamic efficiency, thereby minimizing wind drag and vibration while the cutter is in use.
- **Safety Enhancements:** Injury Prevention: By physically separating the operator and nearby objects from the high-speed blade, the hub significantly lowers the risk of accidental contact and injury.
- **Debris Control:** The hub not only prevents contact with the blade but also helps to contain and redirect debris generated during cutting, reducing the likelihood of objects being thrown outward at high speeds.
- **Maintenance and Inspection:** Modular Design: The hub's design allows for easy removal, inspection, and replacement if necessary. This ensures that any wear or damage can be promptly addressed, maintaining the integrity of the protective barrier over time.
- **Routine Checks:** Incorporating the hub into the maintenance schedule ensures that the safety feature remains in optimal condition and continues to meet regulatory standards.
- **Compliance and Regulatory Benefits:** Safety Standards: The addition of the protective hub

enhances compliance with safety regulations governing the design and operation of outdoor machinery.

- **User Confidence:** With reduced risk of injury, operators can have greater confidence in using the grass cutter, positively impacting both workplace safety and overall machine reliability.

3. Results and Discussion

3.1 Results

Consistent Cutting Performance: The automated system delivered reliable and repeatable cutting results on uniform surfaces, reducing the need for constant human intervention. **Reduced Operator Labor:** By automating the cutting process, the project significantly minimized operator fatigue and dependency on manual adjustments, leading to a more streamlined operation.

Safety Limitations: The absence of sensor-driven obstacle detection and adaptive feedback highlighted potential safety concerns, indicating that operators must remain vigilant during use [6].

Cost Efficiency Achieved: The simplified design reduced initial production and maintenance costs, although further investment in sensor technology might enhance adaptability and overall safety. Figure 3 & 4 Actual Model.



Figure 3 Actual Model

3.2 Future Scope

Advanced Sensor Integration: Integrating technologies such as LIDAR, ultrasonic, or infrared sensors to enable precise, real-time obstacle detection and adaptive terrain response.

AI-Driven Adaptability: Employing machine learning algorithms to analyze cutting patterns and environmental data, allowing the system to optimize blade speed and cutting height for varying vegetation types and terrains.

Renewable Energy Solutions: Incorporating solar panels or other renewable energy sources to extend operating time, reduce reliance on traditional power, and enhance overall energy efficiency.

Remote Monitoring and IoT Connectivity: Enabling IoT integration for remote diagnostics, performance monitoring, and control via smartphone apps or cloud-based platforms, which also supports predictive maintenance.

Enhanced Safety Features: Developing additional automated safety measures such as emergency shut-off, dynamic collision avoidance systems, and real-time alerts to significantly reduce operator risk.

Modular and Upgradeable Design: Designing the system with modular components to allow easy future upgrades, customization for different cutting needs, and simplified maintenance [7].

safeguards users but also contributes to a more balanced and efficient cutting mechanism. This modification reflects a commitment to safety, regulatory compliance, and improved operational performance.

References

- [1]. Anjana, G., Keerthana, G., & Dhanya, N. (2022). Automatic Solar Powered Grass Cutter. Mahalingam College of Engineering and Technology, Pollachi. Retrieved from https://mcet.in/naac/DVV/C1/NAAC_Project_Report_2022/EEE/A10.pdf
- [2]. Chatterjee, S., & Desai, P. (2020). Innovations in Autonomous Garden Equipment: A Case Study on Robotic Lawn Mowers. In Proceedings of the International Conference on Automation and Sustainable Technologies (pp. 78–86).
- [3]. Das, S., & Chandran, M. V. (2022). Design and Fabrication of Solar Powered Grass Cutter. Sathyabama Institute of Science and Technology. Retrieved from https://sist.sathyabama.ac.in/sist_naac/documents/1.3.4/1822-b.e-mech-batchno-31.pdf
- [4]. Engin, A., & Bhat, M. M. (2021). Development of an Autonomous Lawn Mower with Obstacle Detection. Journal of Robotics and Automation, 15(2), 123–130.
- [5]. Kumar, V. B., Sravani, N., Sowmya, S. A., Venu, B., & Harshed, D. (n.d.). Automatic Solar Grass Cutter. St. Martin's Engineering College, Secunderabad, Telangana. Retrieved from <https://www.smec.ac.in/assets/images/committee/research/19-20/AUTOMATIC%20SOLAR%20GRASS%20CUTTER.pdf>
- [6]. Lee, D., & Kim, S. (2019). Smart Lawn
- [7]. Maintenance: Integrating Solar Energy and Autonomous Navigation in Grass Cutting. Renewable and Sustainable Energy Reviews, 103, 204–210.
- [8]. Singh, R., & Patel, K. (2020). Solar-Powered Robotic Grass Cutter: A Sustainable Approach. International Journal of Renewable Energy Research, 9(4), 212–218.



Figure 4 Pictures

Conclusion

The redesign of the grass cutter to include a front-mounted protective hub directly addresses the safety vulnerabilities that were present in the original configuration. By preventing direct blade exposure and reducing debris propulsion, the hub not only